#### for Arduino



### Features:

- RS485 mode (half duplex)
- RS422 mode (full duplex)
- galvanic isolation between Arduino and connected RS485 bus
- Free choice of TX pin between pins 0-5
- Free choice of RX pin between pins 0-5
- Enhanced ESD protection
- adjustable automatic transceiver switching for RS485 mode
- adjustable control of transceiver/receiver via pin 6 or 7
- adjustable Pull-Up, Pull-Down und terminating resistors
- removable block terminal for bus connection
- Indicator LEDs for RX and TX signals
- many options adjustable via DIP switches
- For Arduino UNO and compatible boards

#### for Arduino

## **Applications:**

- Smart Home
- Building Control
- Industrial Control
- Lighting Control
- Video Surveillance

### **Protocols:**

- Modbus
- DMX
- Pelco D
- NMEA0183
- etc

## Terminals:

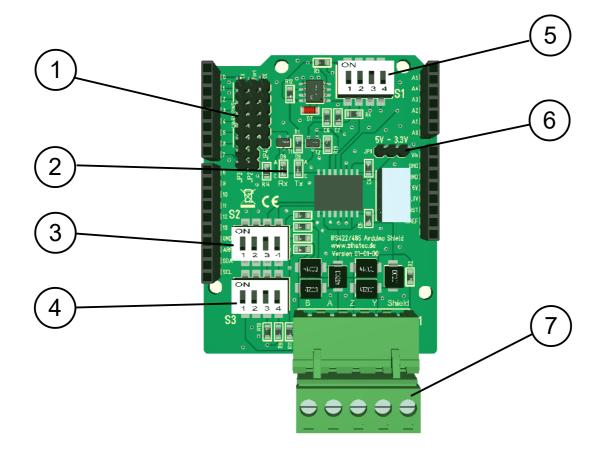
Pin	Meaning	Description	
B*	R-	Receiver inverting input on the bus-side	
A*	R+	Receiver non inverting input on the bus-side	
Z	T-	Driver inverting output	
Y	T+	Driver non inverting output	
Shield	Shield	Shield of cable	

## Please note: In RS485 mode B terminal will be internally connected with Z terminal and A terminal will be connected with Y terminal. Y and Z terminals have no function in RS485 mode.

\* in some older versions the silkscreen marking of B and A terminal is interchanged. In any case the terminal pinout is B, A, Z, Y.

#### for Arduino

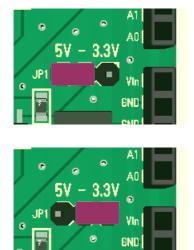
### **Control Elements:**



- ① Jumper for pin selection
- ② Indicator LEDs
- ③ DIP Switch S2
- ④ DIP Switch S3
- ⑤ DIP Switch S1
- 6 Jumper for voltage selection
- ⑦ Removable Terminal Block

for Arduino

## Jumper J1 – voltage settings:



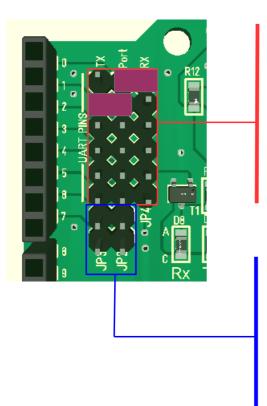
## **5V Selection**

Jumper to left position (default for Arduino Uno)

## 3.3V Selection

Jumper to right position (for example Genuino 101)

## Jumper J2 – J4 pin settings:



## Connection to Tx & Rx Pin

- Jumper to left position Tx
- Jumper to right position Rx

Default;

- Jumper 1st row right
- Jumper 2<sup>nd</sup> row left

## **Tx control Pin**

- no jumper: no pin control
- Jumper to 1st row: pin 6
- Jumper to 2<sup>nd</sup> row: pin 7

Default; - no jumper

#### for Arduino

## S1 - DIP Switch Configuration – send/receive control:

Channel	Description	
1	Receiver always on	
2	Transmitter connected to Receiver	
3	Automatic DE/RE control	
4	DE/RE control via Pin 6 or 7	

#### S2 - DIP Switch Configuration – RS422/485 mode:

Channel	Description	
1	Connect Y to terminal K2	
2	Connect Z to terminal K2	
3	Connect internally Y to A	
4	Connect internally Z to B	

### S3 - DIP Switch Configuration – termination resistors:

Channel	Description	
1	120 Ohm Terminating Resistor On	
2	Not used	
3	4,7k Pull-down Resistor on B	
4	4,7k Pull-up Resistor on A	

#### for Arduino

### Example RS422 mode:

SW1	
1	ON
2	OFF
3	OFF
4	ON *

SW2	
1	ON
2	ON
3	OFF
4	OFF

SW3	
1	ON
2	OFF
3	OFF
4	OFF

## Examples RS485 mode:

Send/receive control via Pin 6 or 7, no terminating resistor

SW1	
1	OFF
2	ON
3	OFF
4	ON *

SW2	
1	OFF
2	OFF
3	ON
4	ON

SW3	
1	OFF
2	OFF
3	OFF
4	OFF

#### automatic send/receive control, multipoint master

SW1	
1	OFF
2	ON
3	ON
4	OFF

SW2	
1	OFF
2	OFF
3	ON
4	ON

SW3	
1	ON
2	OFF
3	ON
4	ON

\* Set Pin 6 or 7 to high level to transmit protocols